

Na aula passada definimos a matriz adjunta de uma matriz quadrada, $A_{n \times n}$, dada por:

$$\text{adj } A = \begin{pmatrix} A_{11} & A_{21} & \vdots & A_{n1} \\ A_{12} & A_{22} & \vdots & A_{n2} \\ \vdots & \vdots & \ddots & \vdots \\ A_{1n} & A_{2n} & \vdots & A_{nn} \end{pmatrix};$$

onde

$$A_{ij} = (-1)^{i+j} \det(M_{ij})$$

Vimos também que se A for invertível, a sua inversa A^{-1} pode ser determinada calculando:

$$A^{-1} = \frac{1}{\det A} \cdot \text{adj } A.$$

Ex: $A = \begin{pmatrix} 1 & 2 & -1 \\ 0 & 2 & 2 \\ -1 & 2 & 3 \end{pmatrix}.$

Verifique se A é invertível. Se for, obtenha sua inversa a partir da matriz adjunta.

Solução:

$$\det(A) = \begin{vmatrix} 1 & 2 & -1 \\ 0 & 2 & 2 \\ -1 & 2 & 3 \end{vmatrix} \begin{vmatrix} 1 & 2 \\ 0 & 2 \\ -1 & 2 \end{vmatrix}$$
$$= \underline{6} - \underline{4} + 0 - \underline{2} - \underline{4} - 0 = \underline{-4} \neq 0.$$

Logo, A é invertível.

Então, $\exists A^{-1} = \frac{1}{\det A} \cdot \text{adj} A$, onde:

$$\text{adj} A = \begin{pmatrix} A_{11} & A_{21} & A_{31} \\ A_{12} & A_{22} & A_{32} \\ A_{13} & A_{23} & A_{33} \end{pmatrix}, \text{ sendo:}$$

$$\bullet A_{11} = (-1)^{1+1} \cdot \det(M_{11}) = + \begin{vmatrix} 2 & 2 \\ 2 & 3 \end{vmatrix} = 6 - 4 = \underline{2}$$

$$\bullet A_{12} = \underline{(-1)^{1+2}} \cdot \det(M_{12}) = - \begin{vmatrix} 0 & 2 \\ -1 & 3 \end{vmatrix} = 0 - (+2) = \underline{-2}$$

$$\bullet A_{13} = (-1)^{1+3} \cdot \det(M_{13}) = + \begin{vmatrix} 0 & 2 \\ -1 & 2 \end{vmatrix} = 0 + 2 = \underline{\underline{2}}$$

$$\bullet A_{21} = (-1)^{2+1} \cdot \det(M_{21}) = - \begin{vmatrix} 2 & -1 \\ 2 & 3 \end{vmatrix} = -(6 + 2) = \underline{\underline{-8}}$$

$$\bullet A_{22} = (-1)^{2+2} \cdot \det(M_{22}) = + \begin{vmatrix} 1 & -1 \\ -1 & 3 \end{vmatrix} = 3 - 1 = \underline{\underline{2}}$$

$$\bullet A_{23} = (-1)^{2+3} \cdot \det(M_{23}) = - \begin{vmatrix} 1 & 2 \\ -1 & 2 \end{vmatrix} = -(2 + 2) = \underline{\underline{-4}}$$

$$\bullet A_{31} = (-1)^{3+1} \cdot \det(M_{31}) = + \begin{vmatrix} 2 & -1 \\ 2 & 2 \end{vmatrix} = 4 + 2 = \underline{\underline{6}}$$

$$\bullet A_{32} = (-1)^{3+2} \cdot \det(M_{32}) = - \begin{vmatrix} 1 & -1 \\ 0 & 2 \end{vmatrix} = -2$$

$$\bullet A_{33} = (-1)^{3+3} \cdot \det(M_{33}) = + \begin{vmatrix} 1 & 2 \\ 0 & 2 \end{vmatrix} = \underline{\underline{2}}$$

Assim, obtemos:

$$\begin{aligned}\underline{A^{-1}} &= \frac{1}{\det A} \cdot \text{adj} \cdot A \\&= \frac{1}{-4} \cdot \begin{pmatrix} 2 & -8 & 6 \\ -2 & 2 & -2 \\ 2 & -4 & 2 \end{pmatrix} = \\&= \begin{pmatrix} -\frac{2}{4} & +\frac{8}{4} & -\frac{6}{4} \\ \frac{2}{4} & -\frac{2}{4} & \frac{2}{4} \\ -\frac{2}{4} & \frac{4}{4} & -\frac{2}{4} \end{pmatrix} \\&= \begin{pmatrix} -\frac{1}{2} & 2 & -\frac{3}{2} \\ \frac{1}{2} & -\frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & 1 & -\frac{1}{2} \end{pmatrix}\end{aligned}$$

TEOREMA (REGRAS DE CRAMER) Seja um sistema linear da forma $Ax = b$, onde

$$A = (a_{ij})_{m \times m}; \quad b = (b_1 \ b_2 \ \dots \ b_m)^t \text{ e}$$

$x = (x_1 \ x_2 \ \dots \ x_m)^t$. Se o sistema possui solução única, ela é dada por:

$$x_i = \frac{\det A_i}{\det A},$$

onde $\det A_i$ é o determinante da matriz obtida de A , substituindo a coluna i pela matriz coluna $b = (b_1 \ b_2 \ \dots \ b_m)^t$.

DEMONSTR.: Suponha o sistema $Ax = b$ nas hipóteses do teorema. Logo, A é invertível. Assim, $\exists A^{-1}$ inversa de A .

[obs.: lembre que o sistema $Ax = b$, se]

expandido, fica:

$$\begin{pmatrix} a_{11} & a_{12} & \dots & a_{1m} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mm} \end{pmatrix} \cdot \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_m \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{pmatrix}$$

$$\Leftrightarrow \begin{cases} a_{11}x_1 + a_{12}x_2 + \dots + a_{1m}x_m = b_1 \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2m}x_m = b_2 \\ \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mm}x_m = b_m \end{cases}$$

Multiplicando à esquerda por A^{-1} , vem:

$$Ax = b$$

$$A^{-1}(Ax) = A^{-1} \cdot b$$

$$\Rightarrow \underbrace{(A^{-1} \cdot A)}_{I''} \cdot x = A^{-1} \cdot b$$

I''

$$x = \underbrace{A^{-1}}_{\text{adj } A} \cdot b$$

$\frac{1}{\det A} \cdot \text{adj } A$

$$\Rightarrow \underset{\sim}{x} = \frac{1}{\det A} \cdot \text{adj} A \cdot b = \underbrace{\frac{\text{adj} A \cdot b}{\det A}} ;$$

oder:

$$\text{adj} A \cdot b = \begin{pmatrix} A_{11} & A_{21} & \dots & A_{m1} \\ A_{12} & A_{22} & \dots & A_{m2} \\ \vdots & \vdots & \ddots & \vdots \\ A_{1n} & A_{2n} & \dots & A_{mn} \end{pmatrix} \cdot \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix}$$

$$= \begin{pmatrix} A_{11} \cdot b_1 + A_{21} \cdot b_2 + \dots + A_{m1} \cdot b_n \\ A_{12} \cdot b_1 + A_{22} \cdot b_2 + \dots + A_{m2} \cdot b_n \\ \vdots \\ A_{1n} \cdot b_1 + A_{2n} \cdot b_2 + \dots + A_{mn} \cdot b_n \end{pmatrix}$$

$$= \begin{pmatrix} \sum_{k=1}^n A_{k1} \cdot b_k \\ \sum_{k=1}^n A_{k2} \cdot b_k \\ \vdots \\ \sum_{k=1}^n A_{kn} \cdot b_k \end{pmatrix}$$

Defina a matriz A_i por: 

$$A_i = \begin{pmatrix} a_{11} & a_{12} \dots a_{1,i-1} & \boxed{b_1} & a_{1,i+1} \dots a_{1m} \\ a_{21} & a_{22} \dots a_{2,i-1} & \boxed{b_2} & a_{2,i+1} \dots a_{2m} \\ \vdots & \vdots & \vdots & \vdots \\ a_{m1} & a_{m2} \dots a_{m,i-1} & \boxed{b_m} & a_{m,i+1} \dots a_{mm} \end{pmatrix}$$

i -ésima coluna de A é substituída pela matriz coluna $b = (b_1, b_2, \dots, b_m)^T$

Desenvolvendo o $\det A_i$ sobre esta i -ésima coluna, temos obter:

$$\det A_i = b_1 \cdot A_{1i} + b_2 \cdot A_{2i} + \dots + b_m \cdot A_{mi} = \sum_{k=1}^m b_k \cdot A_{ki}$$

Analog; tem-se que:

$$x = \frac{\text{adj} \cdot A \cdot b}{\det A} = \frac{1}{\det A} \cdot \begin{pmatrix} \sum_{k=1}^m A_{k1} \cdot b_k \\ \vdots \\ \sum_{k=1}^m A_{km} \cdot b_k \end{pmatrix}$$

$$\Rightarrow \underbrace{x_i} = \frac{\sum_{k=1}^n b_k \cdot \overbrace{A_{ki}}^{\text{Det } A_i}}{\text{Det } A} = \frac{\text{Det } A_i}{\text{Det } A}$$

□

ex.: Resolver, usando a regra de Cramer, o sistema linear:

$$\begin{cases} 2x + y - z = -6 \\ x + 3y + z = 4 \\ x + y - z = 4 \end{cases}$$

Solução:

$$A = \begin{pmatrix} 2 & 1 & -1 \\ 1 & 3 & 1 \\ 1 & 1 & -1 \end{pmatrix}$$

$$\Rightarrow \text{Det } A = \begin{vmatrix} 2 & 1 & -1 & | & 2 & 1 \\ 1 & 3 & 1 & | & 1 & 3 \\ 1 & 1 & -1 & | & 1 & 1 \end{vmatrix} =$$

$$= -6 + 1 - 1 + 3 - 2 + 1 = -4$$

$$\det A_1 = \begin{vmatrix} -6 & 1 & -1 & -6 & 1 \\ 4 & 3 & 1 & 4 & 3 \\ 4 & 1 & -1 & 4 & 1 \end{vmatrix}$$

$$= 18 + 4 - 4 + 12 + 6 + 4 = \underline{\underline{40}}$$

$$\det A_2 = \begin{vmatrix} 2 & -6 & -1 & 2 & -6 \\ 1 & 4 & 1 & 1 & 4 \\ 1 & 4 & -1 & 1 & 4 \end{vmatrix}$$

$$= -8 - 6 - 4 + 4 - 8 - 6 = \underline{\underline{-28}}$$

$$\det A_3 = \begin{vmatrix} 2 & 1 & -6 & 2 & 1 \\ 1 & 3 & 4 & 1 & 3 \\ 1 & 1 & 4 & 1 & 1 \end{vmatrix}$$

$$= 24 + 4 - 6 + 18 - 8 - 4 = \underline{\underline{28}}$$

Por tanto, obtenemos:

$$\underline{x} = \frac{\det A_1}{\det A} = \frac{40}{-4} = \underline{\underline{-10}}$$

$$\underline{y} = \frac{\det A_2}{\det A} = \frac{-28}{-4} = \underline{7}$$

$$\underline{z} = \frac{\det A_3}{\det A} = \frac{28}{-4} = \underline{-7}$$

$$S = \{(x, y, z)\} = \{(-10, 7, -7)\}.$$
